## **COURSE DETAIL**

## **ROBOT VISION**

**Country** Korea, South

Host Institution Seoul National University

**Program(s)** Seoul National University

UCEAP Course Level Upper Division

UCEAP Subject Area(s) Computer Science

UCEAP Course Number

**UCEAP Course Suffix** 

UCEAP Official Title ROBOT VISION

UCEAP Transcript Title ROBOT VISION

**UCEAP Quarter Units** 4.50

**UCEAP Semester Units** 3.00

## **Course Description**

This course covers fundamental concepts in various computer vision topics related to robotics, examining approaches and solutions in visual recognition problems for robots. Topics include 3D environment modeling/3D reconstruction, and object detection, recognition, and tracking using deep learning.

All students must complete an individual project on a related topic. Suggested prerequisites: Linear algebra and probability theory, programming skills.

Language(s) of Instruction English

Host Institution Course Number M3228.003000 001

Host Institution Course Title ROBOT VISION

**Host Institution Campus** 

**Host Institution Faculty** 

Host Institution Degree

**Host Institution Department** 

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