# **COURSE DETAIL**

#### **INTRODUCTION TO AUTONOMOUS MOBILE ROBOTICS**

# **Country**

Ireland

#### **Host Institution**

Trinity College Dublin

# Program(s)

Trinity College Dublin

#### **UCEAP Course Level**

**Upper Division** 

# **UCEAP Subject Area(s)**

Mechanical Engineering

## **UCEAP Course Number**

154

## **UCEAP Course Suffix**

#### **UCEAP Official Title**

INTRODUCTION TO AUTONOMOUS MOBILE ROBOTICS

# **UCEAP Transcript Title**

**AUTON MOBILE ROBOT** 

# **UCEAP Quarter Units**

5.00

#### **UCEAP Semester Units**

3.30

## **Course Description**

This course presents a practical and theoretical introduction to modern autonomous mobile robot systems. It gives students a broad introduction to the field spanning topics including hardware, software, Al and machine learning, and human-robot interaction and robot ethics. Students study the technology and methods underlying a robot's ability to sense and act in its environment. Through a series of labs and assignments, students gain a proficiency in developing applications for robots in both simulation and real-world settings. The course has the following key components: an introduction to mobile robots – sensors, actuators, and control paradigms; the fundamental theory for autonomous mobile robots (kinematics, localization, mapping, and path planning); the scientific methods for evaluating robot performance; an introduction to the field of human-robot interaction; and robots-in-the-wild: case studies of real-world robots and their ethical implications.

## Language(s) of Instruction

English

## **Host Institution Course Number**

MEU44B12

#### **Host Institution Course Title**

INTRODUCTION TO AUTONOMOUS MOBILE ROBOTICS

#### **Host Institution Course Details**

https://www.tcd.ie/media/tcd/engineering/pdfs/current-students/MEU44B12.pdf

#### **Host Institution Campus**

**Host Institution Faculty** 

## **Host Institution Degree**

#### **Host Institution Department**

Engineering

# **Course Last Reviewed**

2024-2025

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